International Symposium on AI Standards: towards trustworthy AI through standards

Human-Machine Co-Evolution System Guidebook

4th/July/2024 Akihisa Morikawa **Project Leader of HMCES Project Director of Imaginary Corporation** Corporate Officer of Service Design Business Area, Witz Corporation



AGINARY

My self-introduction

I specialize in developing highly safety and reliable embedded systems.

- Biography
 - Mainly experienced in new development of embedded software for information home appliances, in-vehicle software PF development, etc.
 - Started functional safety development in 2006. Successful acquisition of IEC 61508 process certification in 2010 for the first time in Japan. Moreover in 2012, ISO 26262 process certification is the first time in the world.
 - Leading business centered on functional safety / product safety / AI safety (supporting more than 100 companies in Japan)
 - Organize methods for conforming to functional safety standards for AI and make international technical proposals (publish technical paper) <u>https://arxiv.org/abs/2008.01263</u>
 - Contributed to the formulation of the AI functional safety standard (ISO/IEC TR 5469) at ISO/IEC JTC1/SC42 WG3
 - November 2022: Publish a book that explains the points of safety assurance measures for AI systems in a story style



三恵社







INDUSTRY-ACADEMIA-GOVERNMENT JOINT RESEARCH: RESEARCH AND DEVELOPMENT OF SAFETY CASE TECHNOLOGIES FOR AL SYSTEMS SUCH AS AUTONOMOUS DRIVING

SEAMS Project https://www.seams-p.jp/

Ministry of Economy, Trade and Industry (METI) Support Project (2017 to 2019)

<Main R&D results>

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- Functional safety design/evaluation patterns for AI systems
 - "Safety design concepts for statistical machine learning components toward accordance with functional safety standards"
 - Akihisa Morikawa (Witz Corp.), Yutaka Matsubara (Nagoya Univ.), <u>https://arxiv.org/abs/2008.01263</u>
- How to quantify uncertainty in AI systems
 - based on IEC/TS 62998-1
- Building a reliable ML development process (procedures, templates and checklists)
 - based on 8.5 of UL 4600, Annex B of ISO/TR 4804, Automotive SPICE v4, etc
- Comprehensive verification method for complex conditions (using virtual simulation)
- Several concrete developments of AI systems

Agenda

1. Technical issues for the future society we envision

2.Our R&D Project "HMCES Project"

3. Human-Machine Co-Evolution System Guidebook

4.On-going tasks

The future society we envision

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Serious problems

<u>in Japan</u>

 Decrease in productivity (aging society, shortened working hours, etc.)
 Low sense of happiness (47th in world happiness ranking)

Advanced symbiotic society of humans and machines (with AI)

- improves well-being by optimizing for each individual
- continues to improve productivity, convenience, safety, and happiness

"Co-Evolution" of humans, machines (Al), and society 1. Not only Al's improvement 2. Changes in human values and behavior

3. Changes in laws, infrastructure, lifestyles



Issues of continuous evolving social system

Technical Issues	Case of conventional systems	Case of co-evolving systems
(1) Verificationtiming of continuouschanging systems	Thoroughly verify before deploying.	Since it is constantly changing, there is no timing for verification.
(2) Quality and safety assurance of unknown systems	Extract unknown risks to the assumed system as much as possible (using Guideword) and implement risk mitigation measures (SOTIF)	It is not convenient to detect deviations from the assumed system (concept drift) and shut down the system.
(3) Human tracking of machine and environmental changes	Compliance with safety operation rules for the assumed system	Humans also need to be flexible to keep up with change.

Guidebook against issues of continuous evolving social system

<Co-evolution Guidebook>

Supporting the Safety and Security of continuous evolving social system

- Establish new design and verification methods
- Guides to enable human flexibility and adaptability



- < Key Existing Technologies >
- Human-Machine Teaming (HMT)
- Human behavior analysis
- · Resilience Engineering (Safety II)
- · Collaborative Safety
- · Other several AI standards (by SC42)



Our guidebook vs Key existing practices

Key practices	Goals to be achieved through co-evolution			l t	Uncertainty about "future change"						
	Safety Improve	Achievement of project	Improved well-	*The s	Entire system Entire system	stem iers from each other		Known knowns	Known Unknowns	Unknown knowns	Unkown Unkowns
	ment	objectives (e.g., increased productivity)	being of stakehol ders	Machine (mechanical/ electronic systems/Al)	Surrounding environment (physical infrastructure)	Regulations and rules (logical infrastructure)	Stakeh olders, includin g users	(Knowing what I know)	(Knowing what I don't know)	(I don't know what I know)	(I don't know what I don't know)
Functional Safety	\checkmark	_	—	\checkmark	—	-	—	\checkmark	—	_	_
SOTIF	\checkmark	-	—	\checkmark	\checkmark	-	—	\checkmark	\checkmark	\checkmark	\checkmark
Collaborative Safety	\checkmark	\checkmark	—	\checkmark	\checkmark	-	\checkmark	\checkmark	—	_	_
Human behavior analysis	-	-	\checkmark	-	-	-	\checkmark	\checkmark	—	_	_
HMT	-	\checkmark	_	\checkmark	-	-	\checkmark	\checkmark	-	_	-
HMCES Guidebook	✓	\checkmark	√	✓	✓	✓	\checkmark	✓	✓	✓	✓
Measures				Measures							
•	Convention There is compre that tak other fa	nal issues : s no ehensive pra ces into acco actors than s	ctice ount afety.	Convent No go the or Safet an ov New risk Comp forest	ional Issues ood practice verall syster y assurance rerall system ss : olex changes een by huma	: s exist to ad n. e methods ha that change s increase ri ans.	apt to co ave not <u>y</u> es frequ sks that	omprehe yet been ently. cannot t	nsive cha establishe pe predicte	nges in ed for ed or	



Organization of HMCES Project

[R&D Budget]

Ministry of Economy, Trade and Industry (METI)

[R&D members]

- WITZ Group
 - Imaginary [Project Leader]
 - Witz
 - Atelier
- Nagoya University [Sub Leader]
- National Institute of Advanced Industrial Science and Technology (AIST)
- Gomes Company

[Management]

The Public Foundation of Chubu Science and Technology Center (CSTC)

[Advisors/Observers]

- Japanese members of ISO/IEC
 JTC1/SC42
- Big maker companies
 - Mitsubishi
 - Suzuki
 - Aisin
 - Kobelco
 - Meiden
 - Hitachi
- Japan Automobile Research Institute (JARI)
- Certification bodies
 - UL Japan
 - DNV



Co-evolutionary pilot system development and evaluation

- Coexistence/collaborative robot development
 - System configuration: Hands (arm robot), feet (AMR), eyes (camera), ears & mouth (Al concierge app)

tion as faithful as possible

- Humans and robots share tasks in a common space
- Each behavior evolves in response to mutual changes, such as improvements in human skills and robot performance.



Positioning of co-evolution necessary for future society



Table of contents of HMCES Guidebook

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- 1.3.1. Unresolved Issues in Existing AI System Guidelines
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- 2.1. Co-evolution System Configuration
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- 3.2.2. Requirements for Machine (AI System) Developers
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Summary of HMCES Guidebook (1/2)

- Defining Co-evolving Systems and Stakeholders
- Definition of the co-evolving system life cycle (based on Figure.3 of ISO/IEC 22989:2022)
- Organize the requirements for human-machine co-evolution for each phase



Summary of HMCES Guidebook (2/2)

Proposal for Evolution Support Measures



2 main roles of virtual space

- Monitoring the real space
 - events and changes that are actually occurring in the field
 - · Known-known events: sufficiently predictable
 - Known-unknown events: not easy but are somewhat predictable
- Simulation for unknown conditions
 - providing an opportunity to take countermeasures in advance
 - Unknown-known events: not clearly known at this time but could occur in the future
 - · Unknown-unknown events: not expected at all



SafeComp2023 presentation and poster

- Presented the Co-Evolution Guidebook at an international conference (SafeComp2023, September 2023) with a presentation and poster booth and received some feedback comments from international experts.
- Toward Human-centered AI Framework: An Introduction to AI2X Co-evolution Project,
 - Yutaka Matsubara, Akihisa Morikawa, Daichi Mizuguchi and Kiyoshi Fujiwara
 - https://safecomp2023.cnrs.fr/position-papers/



Indicators related to human-machine cooperation

- Evaluation indicators are essential to promote, analyze, and improve the co-evolutionary system
 < Base indicators >
- HMT: Common Metrics to Benchmark Human-Machine Teams (HMT): A Review (https://ieeexplore.ieee.org/document/8404030)
- Resilience engineering: Resilience Engineering Indicators and Safety Management: A Systematic Review (https://www.sciencedirect.com/science/article/pii/S2093791120302663)

				Stakeholders				I	l	
Metrics/RE indicators	trics/RE indicators 指標		指標詳細說明		計測可否		Users Developers		Assessors	
1			Users側にしかわからない指標	システム側にしかわからない指標	全体統省しないとわからない指標 (For 全体監視 あるいは ルール)	システム側に提示が望ましい	ユーザ側に提示が望ましい	インフラとして計測が望ましい	第3者による監視が望ましい	
Adaptability	地応性	■開始時間(3時)には、人間の202期に 基づいて抽象的な品質を測定するために使用される。適応性は期間家に よる55時期の評価を用いて測定される。 主朝的な尺度と人間の間性また は特性は、頻繁者の尺度に位在す る。リアルタイムで測定するのは返 業	ー ユーザ評価の尺度は主観となってし まうため計測はできないが、開発例 にとっては重要な指標と思われる。		。 専門家による5的際の評価を用いて 潮走可能。 "Personality, adaptability, and performance: Performance on well-defined problem solving tasks," [102]	○ ユーザの使い勝手に大きな影響を与える指標 と思われる。	-	-	○ 客税的立場でユーザが容易に使用できる操 住などの監測は必要を思われる。	
Assertiveness	自己主張(自傷に満ちた態度)	主報の指標(SM), Rathus の自己 主張尺度[103]. [104]に基づいて 測定される。観察者の尺度に位存す るため、リアルタイムで測定するの は回難。	- m		C Rathus の自己主張尺度[103]、 [104]に基づいて測定可能。 "A 30-item schedule for assessing assertive behavior," [103] "The effects of crit ical team member assertiveness on team performance and satisfaction," (104)					
Composure	激り若き(冷静さ)	人間のパフォーマンスの向上を通じ マテームの結束を高めるための人間 のパフォーマンス属性の一つ。19 の発なる尺度を使用して測定される [105]、[106]、戦略者の尺度に低 許するため、リアルタイムで測定す るのは国際。	-	_	 の異なる尺度を使用して測定される[105]、[106]、 */Academic resilience and the four Cs: Confidence, control, composure, and commitment," [105] "A methodological review of resilience measurement scales," [105] 	○ ユーザの冷静な使用を考慮するのであればシ ステム側への提示は望ましい。	-	_	○ ユーザの使用に関して、客観的立場での監 は必要と思われる。	

Development of verification method for Co-Evolution systems

- Technical study conducted with European safety experts in September 2023
- Examining methods for verifying the safety of ever-changing and unknown systems using specific applications.
- Acquisition technology
 - Tips on modeling, analysis, and evaluation methods for analyzing and evaluating Co-Evolution systems
 - Tips for Formal Verification of Safety of Co-Evolution systems









On-going tasks

- Brush up on the Guidebook
 - Reflecting comments from various experts
 - Feedback from the demonstration experiment (Theme 3)
- Technology building
 - How to use HMT indicators
 - Analysis, verification, and evaluation methods for systems that continue to change or behave in unknown ways

- · Human models on virtual space
- Publication of guidebooks
 - Contribution to standardization activities



THANKS FOR LISTENING!

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